HIGHER TECHNICAL INSTITUTE

MECHANICAL ENGINEERING COURSE

DIPLOMA PROJECT

DESIGN AND IMPLEMENTATION OF A PART RECOGNITION SYSTEM FOR A ROBOT ARM

M/619

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SUMMARY

In the introduction, a brief explanation of what a part recognition system is provided.

As the first objective of the project was to become familiar with the Robot a relevant background on Robots is provided in chapter 2.

In Chapter 3, are explained the different types of Robots that exists and in Chapter 4 the ways that a Robot can be programmed.

In Chapter 5 the reasons for using Robots are explained.

Chapter 6 contains the design criteria for the system.

Chapter 7 contains the methods of part recognition.

Chapter 8 explains how the system operates.

Chapter 9 provides brief information about sensors.

Chapter 10 provides information about the computer interface.

In Chapter 11 the system constructed for the project is explained.

Chapter 12 contains the software developed for the project.

Chapter 13 contains the motions of the robot.

Finally in Chapter 14 are the conclusions of the project.

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MAX 2
DRAWINGS
CYLINDER A1/A2
BASE B1/B2