

CO2 WELDING CONTROLLER

by

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Project Report

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## SUMMARY

TITLE: CO2 WELDING CONTROLLER

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The purpose of the project is to design, construct and test an arm suitable for CO2 WELDING TORCH. The arm and the work surface are driven by stepper motors. Each stepper motor is driven by a stepper motor driver.

The MTB 85-1 is used as a controller element within the system. By using a suitable software and a suitable converter circuit for the RS232C serial port of the PC the 8085 communicates with a PERSONAL COMPUTER and according to the commands of the operator the 8085 executes.

The operator can type the width and the length of the metal to be welded and according to the width the corresponding speed is selected automatically when the motors rotate and the arm is positioned accordingly above work surface.

The operator can also display the width and length and also by typing H a help menu appears on the screen.

The operator also by typing C the same operation is repeated continuously with same data.

## CONTENTS

ACKNOWLEDGEMENTS	i
SUMMARY	ii
INTRODUCTION	iii
CHAPTER 1 - MIG WELDING	1
CHAPTER 2 - THE HARDWARE IN BLOCK DIAGRAM	3
CHAPTER 3 - STEPPER MOTORS	6
CHAPTER 4 - MOTOR DRIVERS	9
CHAPTER 5 - THE MICROPROCESSOR CONTROLLER	14
MICROTARGET BOARD MTB 85-1	15
5.1 THE MICROPROCESSOR	16
5.2 THE STRUCTURE OF THE BUS	25
5.3 MEMORY	27
5.4 INPUT/OUTPUT PORTS	30
5.5 DECODER	33
5.6 LATCH	34
CHAPTER 6 - COMMUNICATION BETWEEN 8085 & PC	36
CHAPTER 7 - THE SOFTWARE	41
POSSIBLE IMPROVEMENTS OF THE PROJECT	60
REFERENCES	61
APPENDICES	62