

JUNE 1994

COMPUTER AIDED ANALYSIS OF SIMPLE MECHANISMS

by

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Project Report Submitted to

the Department of Mechanical Engineering of the Higher Technical Institute

Nicosia - Cyprus

in partial fulfillment of the requirements for the Diploma of

TECHNICIAN ENGINEER in MECHANICAL ENGINEERING

June 1994



I feel the necessity to dedicate this trial to my parents who dint deny to sacrifice anything for the seek of my studies

AKNOWLEDGEMENT

I would really like to express my themal and sincere thanks to:

Mr Demetriou Paraskeva

My supervisor who has guided me in the selection of the information needed for this trial.

Mr Lambros & Mrs Panayiota Theophanous, For their valuable assistance in the typing

George M Zissimos,

Who, through his assistance enabled me to recall that Friends are not ever lost

INTRODUCTION

The introduction of this work is rather philosophical than an engineered text or computer programming text. In briefly explains how the approach to the project had be done and gives an overview of what will be followed.

Adopting the idea that when solving a problem (or defining a statement or studying etc.) start from the general statements and then proceed to the specific areas, had guided me to play a double role. That of the mechanical engineer and that of the programmer.

Taking the part of the mechanical engineer is the man/woman thar will be the final user of what the programmer will produce. He/she either be familiar or not with computers.

The mechanical engineer has in mind what a mechanism is and how to do the calculations as far as the linkage concern. Very general a mechanical engineer knows what a mechanism is and even better what is simple mechanism and he /she is called to carry out some calculations fo it (Either for synthesising or analising).

Moving to the programmer's point of view the below parallelism can be done. In this case the programmer can be thought as the businessman that must study the market to find a need. For the purpose of this project need can be considered the title of the project and what the program is expected to do are the parameters that will define the success of the product in the market.

After the research mentioned above, the programmer must know the theory hided and the equations governed the simple mechanisms (acceleration, velocity, position). Here is where engineering perception interlinks with the programming perception.

Realising this general statement enforced me to organised the project in chapters as explained below.

CHAPTER 1: Is an independent chapter describing the world of mechanisms and their application and uses nowadays.

CHAPTER 2, 3, 4: Are being undertaken with the kinematic analysis of simple mechanisms. In chapter two intication is done on how the approach of graphical synthesis is done.

Chapter 2: Position analysis.

Chapter 3: Velocity analysis. Chapter 4: Acceleration analysis.

CHAPTER 5: Starts with a synopsis of what had been predecessised in chapters2, 3, 4 and explains the connection with a computer language. Note that in thischapter an introduction Visual Basic is done.

CHAPTER 6: Gives an overall conclusion of the work and a suggestion for posiible future expansion of this program.

Finally, in loose notes the manual and coding of this pogram is presenting

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